

Multiple Linear Regression

Introduction to Statistical Learning
Bachelor in Global Governance
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INTRODUCTION

- Regression models are used to describe how one or perhaps a few response variables depend on other explanatory variables.
- The idea of regression is at the core of much statistical modelling, because the question *what happens to y when x varies?* is central to many investigations.
- It is often required to predict or control future responses by changing the other variables, or to gain an understanding of the relation between them.
- There is usually a single response, treated as random. Often there are many explanatory variables, which are treated as non-stochastic.

If we denote the response by y and the explanatory variables by x , our concern is how changes in x affect y . Given (y_j, x_j) for $j = 1, \dots, n$, in the previous lecture we fitted the straight-line regression model

$$y_j = \beta_1 + \beta_2 x_j + \epsilon_j \text{ for } j = 1, \dots, n$$

An immediate generalization is to increase the covariates,

$$y_j = \beta_1 x_{j1} + \beta_2 x_{j2} + \dots, \beta_p x_{jp} + \epsilon_j = x_j^t \beta + \epsilon_j \quad j = 1, \dots, n$$

where $x_j^t = (x_{j1}, \dots, x_{jp})$ is a $1 \times p$ vector of covariates associated with the j th response, β is a $p \times 1$ vector of unknown parameters and ϵ_j is an unobserved error accounting for the discrepancy between the observed response y_j and $x_j^t \beta$.

Warning: In these slides we simplify notation by using y to represent both the response variable and the value it takes

MATRIX NOTATION

Set

$$x_j = \begin{bmatrix} x_{j1} \\ \vdots \\ x_{jr} \\ \vdots \\ x_{jp} \end{bmatrix} \quad j = 1, \dots, n, \quad \beta = \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_r \\ \vdots \\ \beta_p \end{bmatrix}$$

$$y = \begin{bmatrix} y_1 \\ \vdots \\ y_j \\ \vdots \\ y_n \end{bmatrix} \quad X = \begin{bmatrix} x_1^t \\ \vdots \\ x_j^t \\ \vdots \\ x_n^t \end{bmatrix} = \begin{bmatrix} x_{11} & \dots & x_{1r} & \dots & x_{1p} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{j1} & \dots & x_{jr} & \dots & x_{jp} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} & \dots & x_{nr} & \dots & x_{np} \end{bmatrix} \quad \epsilon = \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_j \\ \vdots \\ \epsilon_n \end{bmatrix},$$

the linear regression model with *design matrix* X can be written as

$$y = X\beta + \epsilon$$

In extended form:

$$\begin{aligned}y_1 &= \beta_1 \cdot x_{11} + \dots + \beta_r \cdot x_{1r} + \dots + \beta_p \cdot x_{1p} + \epsilon_1 \\ &\quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \\ y_j &= \beta_1 \cdot x_{j1} + \dots + \beta_r \cdot x_{jr} + \dots + \beta_p \cdot x_{jp} + \epsilon_j \\ &\quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \\ y_n &= \beta_1 \cdot x_{n1} + \dots + \beta_r \cdot x_{nr} + \dots + \beta_p \cdot x_{np} + \epsilon_n\end{aligned}$$

With $x_1^t = [1, \dots, 1]$, so that:

$$\begin{aligned}y_1 &= \beta_1 + \dots + \beta_r \cdot x_{1r} + \dots + \beta_p \cdot x_{1p} + \epsilon_1 \\ &\quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \\ y_j &= \beta_1 + \dots + \beta_r \cdot x_{jr} + \dots + \beta_p \cdot x_{jp} + \epsilon_j \\ &\quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \\ y_n &= \beta_1 + \dots + \beta_r \cdot x_{nr} + \dots + \beta_p \cdot x_{np} + \epsilon_n\end{aligned}$$

STRAIGHT-LINE REGRESSION IN MATRIX NOTATION

For the straight line regression model $y_j = \beta_1 + \beta_2 x_j + \epsilon_j$ for $j = 1, \dots, n$, the matrix form of the model is

$$\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} + \begin{pmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{pmatrix}$$

so X is an $n \times 2$ matrix and β a 2×1 vector of parameters.

LEAST SQUARE ESTIMATES

The least square estimate of β is obtained by the value that minimizes the *sum of squares*

$$SS(\beta) = \sum_{j=1}^n (y_j - x_j^t \beta)^2 = (y - X\beta)^t (y - X\beta)$$

We obtain the least square estimate of β by solving the equations

$$\frac{\partial SS(\beta)}{\partial \beta_1} = -2 \sum_{j=1}^n (y_j - x_j^t \beta) x_{j1} = 0$$

\vdots

$$\frac{\partial SS(\beta)}{\partial \beta_r} = -2 \sum_{j=1}^n (y_j - x_j^t \beta) x_{jr} = 0$$

\vdots

$$\frac{\partial SS(\beta)}{\partial \beta_p} = -2 \sum_{j=1}^n (y_j - x_j^t \beta) x_{jp} = 0$$

In matrix form these amount to the equations

$$(y - X\beta)^t X = (0, \dots, 0)$$

that is

$$X^t(y - X\beta) = 0$$

which imply that the estimate satisfies

$$X^t y = X^t X \beta$$

Provided the $p \times p$ $X^t X$ is of **full rank**

$$\hat{\beta} = (X^t X)^{-1} X^t y$$

is the system solution.

In simple cases it is possible to have analytical expressions for the least square estimates. For example in the straight-line regression model the X matrix of the representation $y = X\beta + \epsilon$ is

$$X = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix}.$$

Then we have that

$$X^t X = \begin{pmatrix} n & \sum_{j=1}^n x_j \\ \sum_{j=1}^n x_j & \sum_{j=1}^n x_j^2 \end{pmatrix} \quad X^t y = \begin{pmatrix} \sum_{j=1}^n y_j \\ \sum_{j=1}^n x_j y_j \end{pmatrix}$$

After some algebra we obtain

$$\hat{\beta} = \begin{pmatrix} \bar{y} - \bar{x} s_{xy}/s_x \\ s_{xy}/s_x \end{pmatrix}$$

FITTED VALUES AND RESIDUALS

The sum of squares $SS(\beta)$ plays a central role. Its minimum value

$$SS(\hat{\beta}) = \sum_{j=1}^n (y_j - x_j^t \hat{\beta})^2 = (y - X\hat{\beta})^2 (y - \hat{\beta})$$

is called **residual sum of squares**. It is the squared discrepancy between the observations y and the **fitted values** $\hat{y} = X\hat{\beta}$.

The vector $\hat{y} = X\hat{\beta}$ is the linear combination of the columns of X that minimizes the squared distance with the data y .

Note that

$$\hat{y} = X\hat{\beta} = X(X^t X)^{-1} X^t y = Hy$$

The matrix $H = X(X^t X)^{-1} X^t$ is called *hat matrix* or *projection matrix*

The unobservable error $\epsilon_j = y_j - x_j^t\beta$ is estimated by the j th **residual**

$$e_j = y_j - x_j^t\hat{\beta}$$

In vector terms,

$$e = y - x\hat{\beta} = y - Hy = (I - H)y$$

where I is the $n \times n$ identity matrix.

Assuming that $E(\epsilon_j) = 0$ and $Var(\epsilon_j) = \sigma^2 = E(\epsilon_j^2)$ for $j = 1, \dots, n$ we can estimate σ^2 with

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{j=1}^n e_j^2 = \frac{e^t e}{n} = \frac{(y - \hat{y})^t (y - \hat{y})}{n}$$

TWO GROUPS COMPARISON

Suppose that the response variable y has been observed on two groups of observations of size n_1 and n_2 . Let y_{1j} for $j = 1, \dots, n_1$ be the observations of the first group and let y_{2j} for $j = 1 \dots n_2$ be the observation of the second group.

Let β_1 and $\beta_1 + \beta_2$ be the means of the variable y in the two groups.
Hence

$$y_{1j} = \beta_1 + \epsilon_{1j} \quad j = 1, \dots, n_1$$

$$y_{2j} = \beta_1 + \beta_2 + \epsilon_{2j} \quad j = 1 \dots n_2$$

We can write the model for the two groups comparison in matrix notation $y = X\beta + \epsilon$ where

$$y = \begin{pmatrix} y_{11} \\ \vdots \\ y_{1n_1} \\ y_{21} \\ \vdots \\ y_{2n_2} \end{pmatrix} \quad X = \begin{pmatrix} 1 & 0 \\ \vdots & \vdots \\ 1 & 0 \\ 1 & 1 \\ \vdots & \vdots \\ 1 & 1 \end{pmatrix} \quad \beta = \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} \quad \epsilon = \begin{pmatrix} \epsilon_{11} \\ \vdots \\ \epsilon_{1n_1} \\ \epsilon_{2n_1} \\ \vdots \\ \epsilon_{2n_2} \end{pmatrix}$$

For this model we have

$$\hat{\beta} = (X^t X)^{-1} X^t y = \begin{pmatrix} \bar{y}_1 \\ \bar{y}_2 - \bar{y}_1 \end{pmatrix}$$

The two groups comparison can be extended to more than two groups

$$y_{1j} = \beta_1 + \epsilon_{1j} \quad j = 1, \dots, n_1$$

$$y_{2j} = \beta_1 + \beta_2 + \epsilon_{2j} \quad j = 1 \dots n_2$$

$$\vdots \quad \vdots \quad \vdots$$

$$y_{kj} = \beta_1 + \beta_k + \epsilon_{kj} \quad j = 1 \dots n_k$$

Let $y_j = (y_{j1}, \dots, y_{jn_j})^t$ for $j = 1, \dots, k$.

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_k \end{pmatrix} \quad X = \begin{pmatrix} 1_{n_1} & 0_{n_1} & \cdots & 0_{n_1} \\ 1_{n_2} & 1_{n_2} & \cdots & 0_{n_1} \\ \vdots & & \ddots & \\ 1_{n_k} & 0_{n_k} & \cdots & 1_{n_k} \end{pmatrix}$$

$$\hat{\beta} = (X^t X)^{-1} X^t y = \begin{pmatrix} \bar{y}_1 \\ \bar{y}_2 - \bar{y}_1 \\ \vdots \\ \bar{y}_k - \bar{y}_1 \end{pmatrix}$$

SOME IMPORTANT QUESTIONS

When we perform multiple linear regression, we usually are interested in answering a few important questions.

- 1 Is at least one of the predictors x_1, x_2, \dots, x_p useful in predicting the response?
- 2 Do all the predictors help to explain y , or is only a subset of the predictors useful?
- 3 How well does the model fit the data?
- 4 Given a set of predictor values, what response value should we predict, and how accurate is our prediction?

IS AT LEAST ONE OF THE PREDICTORS USEFUL?

In the simple linear regression setting, in order to determine whether there is a relationship between the response and the predictor we can simply check whether $\beta_1 = 0$. In the multiple regression setting with p predictors, we need to ask whether all of the regression coefficients are zero, i.e. whether $\beta_1 = \beta_2 = \dots = \beta_p = 0$. We test the null hypothesis

$$H_0 : \beta_1 = \beta_2 = \dots = \beta_p = 0$$

versus the alternative

$$H_1 : \text{at least one } \beta_j \text{ is non-zero.}$$

This hypothesis test is performed by computing the F-statistic:

$$F = \frac{(TSS - RSS)/p}{RSS/(n - p - 1)}$$

POTENTIAL PROBLEMS

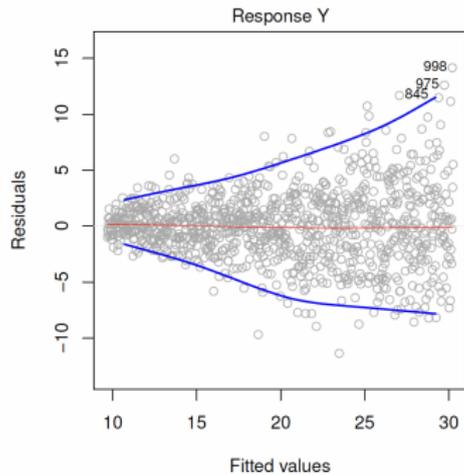
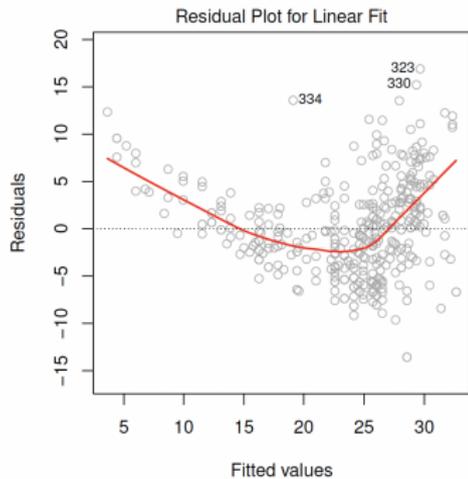
When we fit a linear regression model to a particular data set, many problems may occur. Most common among these are the following:

- 1 Non-linearity of the response-predictor relationships
- 2 Correlation of error terms.
- 3 Non-constant variance of error terms.
- 4 Outliers.
- 5 High-leverage points.
- 6 Collinearity.

RESIDUAL PLOTS

Residual plots are a useful graphical tool for identifying non-linearity. Given a simple linear regression model, we can plot the residuals, $e_i = y_i - \hat{y}_i$, versus the predictor x_i . In the case of a multiple regression model, since there are multiple predictors, we instead plot the residuals versus the predicted (or fitted) values \hat{y}_i .

Ideally, the residual plot will show no discernible pattern. The presence of a pattern may indicate a problem with some aspect of the linear model.



MULTICOLLINEARITY PROBLEM

- Multicollinearity (collinearity) is a phenomenon in which one predictor variable in a multiple regression model can be linearly predicted from the others with a substantial degree of accuracy. In this situation, the coefficient estimates of the multiple regression may change erratically in response to small changes in the model or the data.
- Let consider a $(n \times p)$ design matrix X ; if $|\text{cor}(x_i, x_j)| = 1$ for $i \neq j$ and $i, j \in \{1, p\}$, then there is **perfect collinearity** and the product matrix $X^t X$ is not invertible.

LIFE CYCLE SAVINGS DATA

LifeCycleSavings is data set 5 with variables observed on 50 different countries.
The variables are:

- **sr** aggregate personal savings,
- **pop15** % of population under 15,
- **pop75** % of population over 75,
- **dpi** real per-capita disposable income,
- **ddpi** % growth rate of dpi

	sr	pop15	pop75	dpi	ddpi
Australia	11.43	29.35	2.87	2329.68	2.87
Austria	12.07	23.32	4.41	1507.99	3.93
Belgium	13.17	23.80	4.43	2108.47	3.82
Bolivia	5.75	41.89	1.67	189.13	0.22
Brazil	12.88	42.19	0.83	728.47	4.56
Canada	8.79	31.72	2.85	2982.88	2.43
Chile	0.60	39.74	1.34	662.86	2.67
China	11.90	44.75	0.67	289.52	6.51
Colombia	4.98	46.64	1.06	276.65	3.08
:	:	:	:	:	:
Turkey	5.13	43.42	1.08	389.66	2.96
Tunisia	2.81	46.12	1.21	249.87	1.13
United Kingdom	7.81	23.27	4.46	1813.93	2.01
United States	7.56	29.81	3.43	4001.89	2.45
Venezuela	9.22	46.40	0.90	813.39	0.53
Zambia	18.56	45.25	0.56	138.33	5.14
Jamaica	7.72	41.12	1.73	380.47	10.23
Uruguay	9.24	28.13	2.72	766.54	1.88
Libya	8.89	43.69	2.07	123.58	16.71
Malaysia	4.71	47.20	0.66	242.69	5.08

The data set is available in R

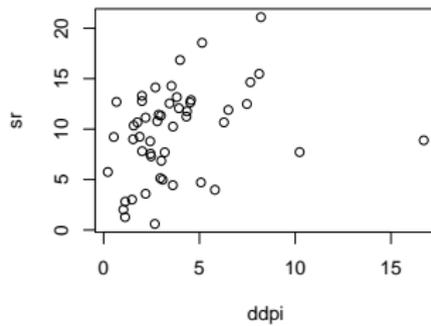
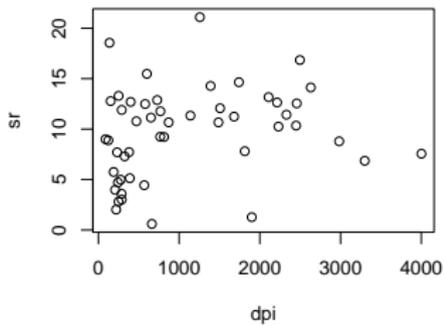
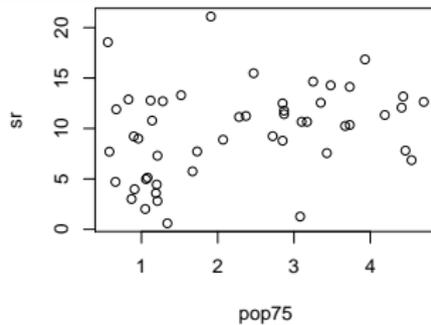
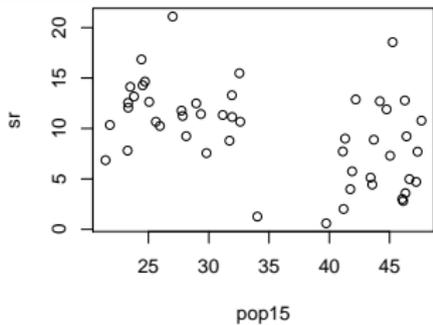
```
> summary(LifeCycleSavings)
```

sr	pop15	pop75	dpi
Min. : 0.600	Min. :21.44	Min. :0.560	Min. : 88.94
1st Qu.: 6.970	1st Qu.:26.21	1st Qu.:1.125	1st Qu.: 288.21
Median :10.510	Median :32.58	Median :2.175	Median : 695.66
Mean : 9.671	Mean :35.09	Mean :2.293	Mean :1106.76
3rd Qu.:12.617	3rd Qu.:44.06	3rd Qu.:3.325	3rd Qu.:1795.62
Max. :21.100	Max. :47.64	Max. :4.700	Max. :4001.89

ddpi
Min. : 0.220
1st Qu.: 2.002
Median : 3.000
Mean : 3.758
3rd Qu.: 4.478
Max. :16.710

Under the life-cycle savings hypothesis as developed by Franco Modigliani, the savings ratio (aggregate personal saving divided by disposable income) is explained by per-capita disposable income, the percentage rate of change in per-capita disposable income, and two demographic variables: the percentage of population less than 15 years old and the percentage of the population over 75 years old.

The data are averaged over the decade 1960-1970 to remove the business cycle or other short-term fluctuations.



In this case we might fit the model

$$y_j = \beta_1 + \beta_2 x_{2j} + \beta_3 x_{3j} + \beta_4 x_{4j} + \beta_5 x_{5j} + \epsilon_j$$

where y is the saving ratio and x_2, x_3, x_4 and x_5 are the variables pop15, pop75, dpi and ddpi. Looking the data we may expect a negative value for β_2 and a positive value for β_5 while the relationship between the saving ratio and the variables pop75 and dpi is not clear. The X matrix has dimension 50×5 and is

$$\begin{pmatrix} 1 & 29.35 & 2.87 & 2329.68 & 2.87 \\ 1 & 23.32 & 4.41 & 1507.99 & 3.93 \\ 1 & 23.80 & 4.43 & 2108.47 & 3.82 \\ 1 & 41.89 & 1.67 & 189.13 & 0.22 \\ 1 & 42.19 & 0.83 & 728.47 & 4.56 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 28.13 & 2.72 & 766.54 & 1.88 \\ 1 & 43.69 & 2.07 & 123.58 & 16.71 \\ 1 & 47.20 & 0.66 & 242.69 & 5.08 \end{pmatrix}$$

In R we can find the fitted values and the residual in the following way.

```
> m=lm(sr~pop15+pop75+dpi+ddpi,data=LifeCycleSavings)
> fitted(m)
```

Australia	Austria	Belgium	Bolivia	Brazil
10.566420	11.453614	10.951042	6.448319	9.327191
Canada	Chile	China	Colombia	Costa Rica
9.106892	8.842231	9.363964	6.431707	5.654922
Denmark	Ecuador	Finland	France	Germany
11.449761	5.995631	12.921086	10.164528	12.730699
Greece	Guatamala	Honduras	Iceland	India
13.786168	6.365284	6.989976	7.480582	8.491326
Ireland	Italy	Japan	Korea	Luxembourg
7.948869	12.353245	15.818514	10.086981	12.020807
Malta	Norway	Netherlands	New Zealand	Nicaragua
12.505090	11.121785	14.224454	8.384445	6.653603
Panama	Paraguay	Peru	Philippines	Portugal
7.734166	8.145759	6.160559	6.104992	13.258445
South Africa	South Rhodesia	Spain	Sweden	Switzerland
10.656834	12.008566	12.441156	11.120283	11.643174
Turkey	Tunisia	United Kingdom	United States	Venezuela
7.795682	5.627920	10.502413	8.671590	5.587482
Zambia	Jamaica	Uruguay	Libya	Malaysia
8.809086	10.738531	11.503827	11.719526	7.680869

> residuals(m)

Australia	Austria	Belgium	Bolivia	Brazil
0.8635798	0.6163860	2.2189579	-0.6983191	3.5528094
Canada	Chile	China	Colombia	Costa Rica
-0.3168924	-8.2422307	2.5360361	-1.4517071	5.1250782
Denmark	Ecuador	Finland	France	Germany
5.4002388	-2.4056313	-1.6810857	2.4754718	-0.1806993
Greece	Guatamala	Honduras	Iceland	India
-3.1161685	-3.3552838	0.7100245	-6.2105820	0.5086740
Ireland	Italy	Japan	Korea	Luxembourg
3.3911306	1.9267549	5.2814855	-6.1069814	-1.6708066
Malta	Norway	Netherlands	New Zealand	Nicaragua
2.9749098	-0.8717854	0.4255455	2.2855548	0.6463966
Panama	Paraguay	Peru	Philippines	Portugal
-3.2941656	-6.1257589	6.5394410	6.6750084	-0.7684447
South Africa	South Rhodesia	Spain	Sweden	Switzerland
0.4831656	1.2914342	-0.6711565	-4.2602834	2.4868259
Turkey	Tunisia	United Kingdom	United States	Venezuela
-2.6656824	-2.8179200	-2.6924128	-1.1115901	3.6325177
Zambia	Jamaica	Uruguay	Libya	Malaysia
9.7509138	-3.0185314	-2.2638273	-2.8295257	-2.9708690

```
> m=lm(sr~pop15+pop75+dpi+ddpi,data=LifeCycleSavings)
> summary(m)
```

Residuals:

Min	1Q	Median	3Q	Max
-8.2422	-2.6857	-0.2488	2.4280	9.7509

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)	
(Intercept)	28.5660865	7.3545161	3.884	0.000334	***
pop15	-0.4611931	0.1446422	-3.189	0.002603	**
pop75	-1.6914977	1.0835989	-1.561	0.125530	
dpi	-0.0003369	0.0009311	-0.362	0.719173	
ddpi	0.4096949	0.1961971	2.088	0.042471	*

Residual standard error: 3.803 on 45 degrees of freedom
Multiple R-squared: 0.3385, Adjusted R-squared: 0.2797

SUMMARY

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 - R^2 or Adjusted R^2
 - t-test
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- 5 interpretation

```

> cor(X)
      pop15      pop75      dpi      ddp
pop15 1.00000000 -0.90847871 -0.7561881 -0.04782569
pop75 -0.90847871 1.00000000 0.7869995 0.02532138
dpi   -0.75618810 0.78699951 1.0000000 -0.12948552
ddp   -0.04782569 0.02532138 -0.1294855 1.00000000

> m=lm(sr~pop15+ddpi,data=LifeCycleSavings)
> summary(m)

Residuals:
    Min       1Q   Median       3Q      Max
-7.5831 -2.8632  0.0453  2.2273 10.4753

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept) 15.59958    2.33439   6.682 2.48e-08 ***
pop15       -0.21638    0.06033  -3.586 0.000796 ***
ddpi        0.44283    0.19240   2.302 0.025837 *
---
Residual standard error: 3.861 on 47 degrees of freedom
Multiple R-squared:  0.2878, Adjusted R-squared:  0.2575

```

