

# Information Theory



MACHINE LEARNING AND AI

# Topics

Entropy as an Information Measure

Entropy for discrete and continuous distributions

Maximum Entropy

Conditional Entropy

Relative entropy: Kullback-Leibler Divergence

Mutual Information

# Information Measure

How much information is received when we observe a specific value for a discrete random variable  $x$  ?

Amount of information is degree of surprise

- Certain means no information
- More information when event is unlikely

# Information Measure

Depends on probability distribution  $p(x)$ ,

A quantity  $h(x)$  can be defined

If there are two unrelated events  $x$  and  $y$  we want  $h(x,y) = h(x) + h(y)$

Thus we choose  $h(x) = -\log_2 p(x)$

- Negative assures that information measure is positive

# Information Measure

Average amount of information transmitted is the expectation wrt  $p(x)$   
referred to as entropy

$$H(x) = - \sum_x p(x) \log_2 p(x)$$

# Entropy

- Uniform Distribution
  - Random variable  $x$  has 8 possible states, each equally likely
    - We would need 3 bits to transmit
    - Also,  $H(x) = -8 \times (1/8) \log_2(1/8) = 3 \text{ bits}$

# Entropy

- Non-uniform Distribution
  - If  $x$  has 8 states with probabilities
  - $(1/2, 1/4, 1/8, 1/16, 1/64, 1/64, 1/64, 1/64)$
  - $H(x) = 2 \text{ bits}$
- Non-uniform distribution has smaller entropy than uniform distribution

## Relationship of Entropy to Code Length

Take advantage of non-uniform distribution to use shorter codes for more probable events, at the expense of longer codes for the less probable events, in the hope of getting a shorter average code length.

- If  $x$  has 8 states  $(a,b,c,d,e,f,g,h)$  with probabilities

$(1/2, 1/4, 1/8, 1/16, 1/64, 1/64, 1/64, 1/64)$

Can use codes

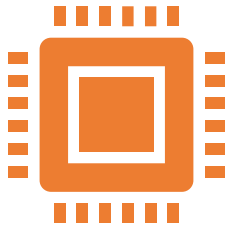
$0, 10, 110, 1110, 111100, 111101, 111110, 111111$

$$\begin{aligned} \text{average code length} &= (1/2)1 + (1/4)2 + (1/8)3 \\ &\quad + (1/16)4 + 4(1/64)6 \\ &= 2 \text{ bits} \end{aligned}$$

- Same as entropy of the random variable

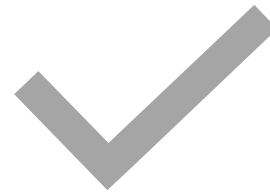


# Relationship between Entropy and Shortest Coding Length



## Noiseless coding theorem of Shannon

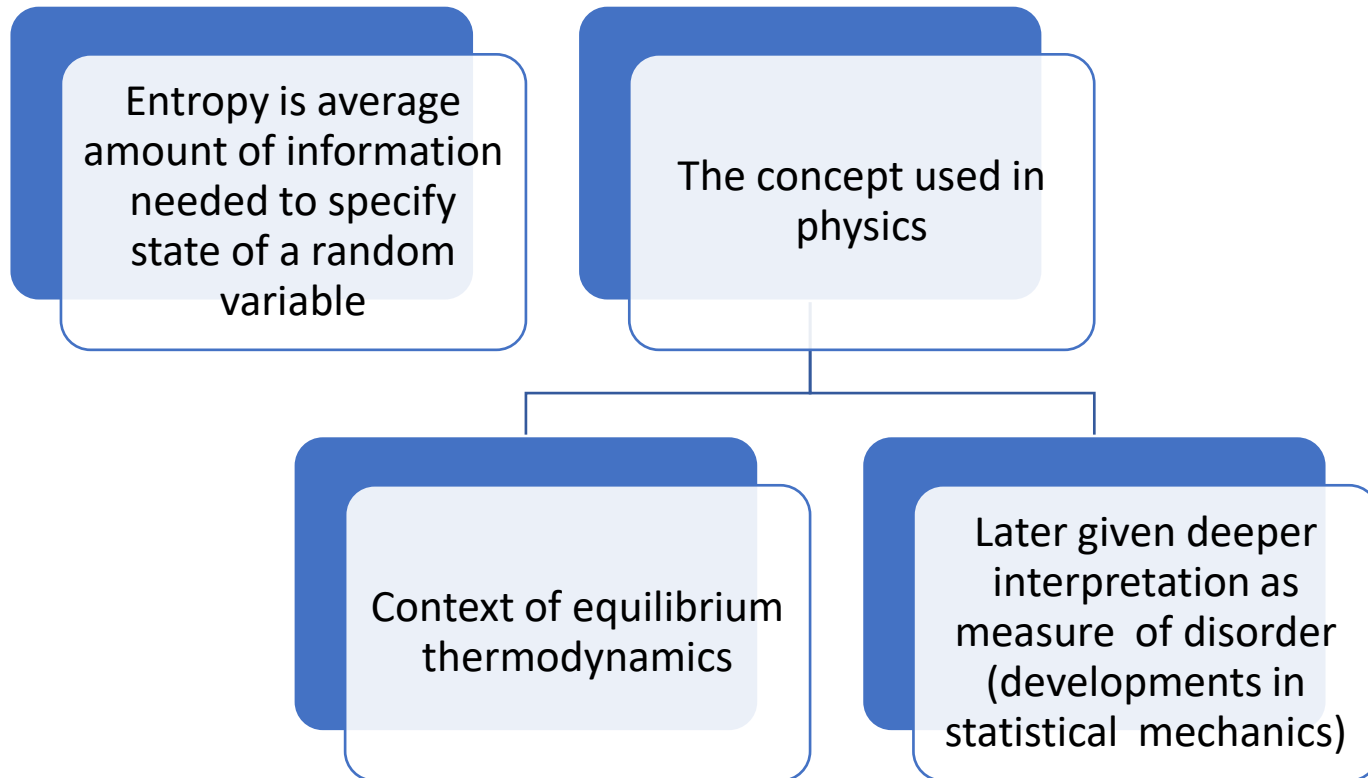
*Entropy is a lower bound on number of bits needed to transmit a random variable*



## Natural logarithms are used in relationship to other topics

Nats instead of bits

# History: Thermodynamics to Information Theory



# History of Entropy

- Ludwig Eduard Boltzmann (1844-1906)
  - Created Statistical Mechanics
    - First law: conservation of energy
      - Energy not destroyed but converted from one form to other
    - Second law: principle of decay in nature—entropy increases
      - Explains why not all energy is available to do useful work
    - Relate macro state to statistical behavior of microstate
- Claude Shannon (1916-2001)
- Stephen Hawking (Gravitational Entropy)



# Entropy

- $N$  objects into bins so that  $n_i$  are in  $i^{\text{th}}$  bin where

- $$\sum_i n_i = N$$

- No of different ways of allocating objects to bins
  - $N$  ways to choose first,  $N-1$  ways for second leads to  $N.(N-1) \dots 2.1 = N!$
  - We don't distinguish between rearrangements within each bin
    - In  $i^{\text{th}}$  bin there are  $n_i!$  ways of reordering objects
  - Total no of ways of allocating  $N$  objects to bins is  $W = \frac{N!}{\prod_i n_i!}$ 
    - Called Multiplicity (also weight of macrostate)

# Entropy

- Entropy: scaled log of multiplicity  $H = \frac{1}{N} \ln W = \frac{1}{N} \ln N! - \frac{1}{N} \sum_i \ln n_i!$ 
  - Sterlings approx as  $N \rightarrow \infty \ln N! \approx N \ln N - N$
  - Which gives  $H = - \lim_{N \rightarrow \infty} \sum_i \left( \frac{n_i}{N} \right) \ln \left( \frac{n_i}{N} \right) = - \sum_i p_i \ln p_i$
- Overall distribution, as ratios  $n_i/N$ , called *macrostate*
- In physics, specific arrangement of objects in bin is *microstate*

# Entropy

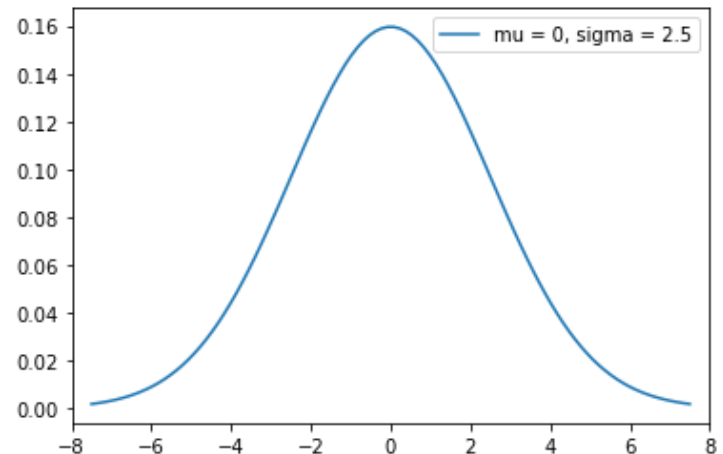
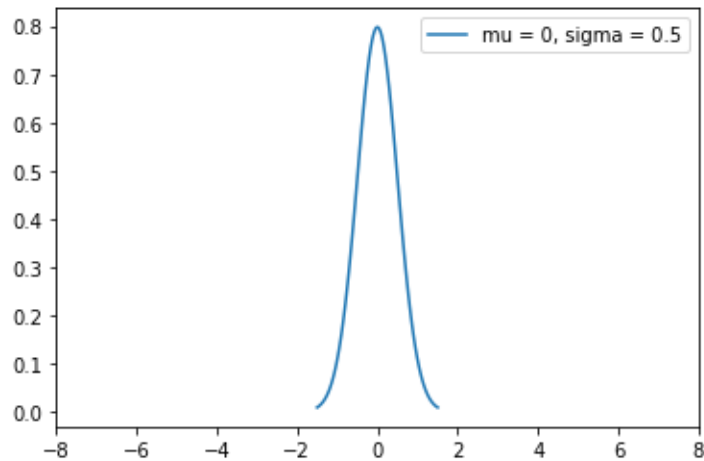
- If  $X$  can take one of  $M$  values (bins, states) and  $p(X=x_i)=p_i$  then

$$H(p)=-\sum_i p_i \ln p_i$$

- Minimum value of entropy is 0 when one of the  $p_i=1$  and other  $p_i$  are 0

$$(\lim_{p \rightarrow 0} p \ln p = 0)$$

# Entropy



- Sharply peaked distribution has low entropy
- Distribution spread more evenly will have higher entropy

# Maximum Entropy

- Found by maximizing  $H$  using Lagrange multiplier to enforce constraint of probabilities
- Maximize

$$H = -\sum p(x) \ln p(x) + \lambda(\sum p(x_i) - 1)$$



# Maximum Entropy

- Solution: all  $p(x_i)$  are equal or  $p(x_i)=1/M$   *$M=no$  of states*
- Maximum value of entropy is:  $\ln M$
- To verify it is a maximum, evaluate second derivative of entropy  $\frac{\partial^2 \tilde{H}}{\partial p(x_i) \partial p(x_j)} = -I_{ij} \frac{1}{p_i}$ 
  - where  $I_{ij}$  are elements of identity matrix

# Entropy with Continuous Variable

- Divide  $x$  into bins of width  $\Delta$
- For each bin there must exist a value  $x_i$  such that

$$\int_{i\Delta}^{(i+1)\Delta} p(x) d(x) = p(x_i)\Delta$$

- Gives a discrete distribution with probabilities  $p(x_i)\Delta$
- Entropy  $H_{\Delta} = -\sum p(x_i)\Delta \ln(p(x_i)\Delta) = -\sum p(x_i)\Delta \ln p(x_i) - \ln \Delta$
- Omit the second term and consider the limit  $\Delta \rightarrow 0$

$$H_{\Delta} = -\int p(x) \ln p(x) dx$$

# Entropy with continuous variable

$$H_{\Delta} = -\int p(x) \ln p(x) dx$$

- Known as Differential Entropy
- *Discrete and Continuous forms of entropy differ by quantity  $\ln \Delta$  which diverges*
  - Reflects to specify continuous variable very precisely requires a large no of bits

# Entropy with Multiple Continuous Variables

- Differential Entropy for multiple continuous variables

$$H(\mathbf{x}) = -\int p(\mathbf{x}) \ln p(\mathbf{x}) d\mathbf{x}$$

- For what distribution is differential entropy maximized?
  - For discrete distribution, it is uniform
  - For continuous, it is Gaussian

# Entropy as Functional

Ordinary calculus  
deals with functions

*A functional* is an  
operator that takes a  
function as input  
and returns a scalar

# Entropy as functional

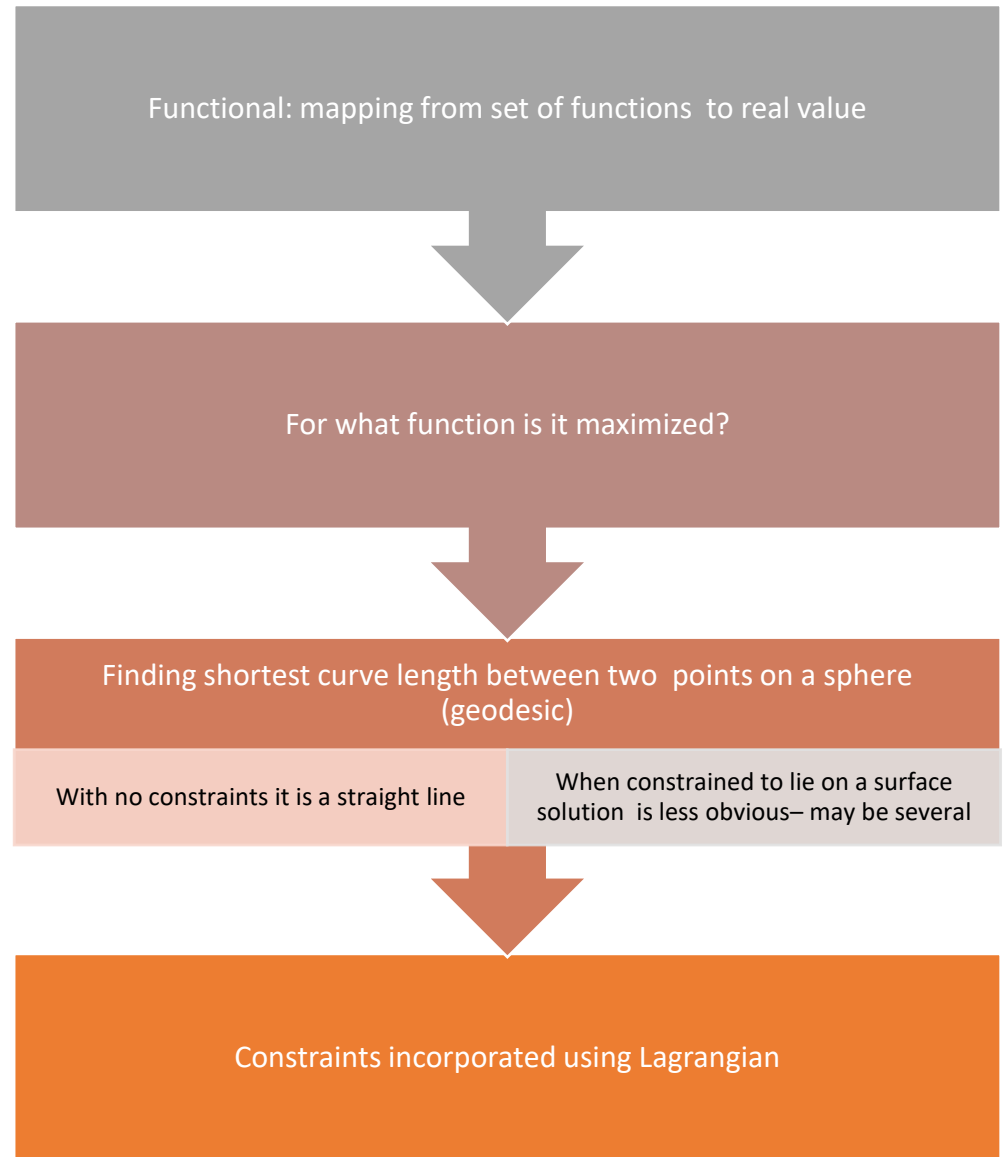
A widely used functional in machine learning is entropy  $H[p(x)]$  which is a scalar quantity



We are interested in the maxima and minima of functionals analogous to those for functions

Called calculus of variations

# Maximising Entropy as Functional



# Maximising Differential Entropy

- Assuming constraints on first and second moments of  $p(x)$  as well as normalization

$$\int p(x)dx = 1 \quad \int xp(x)dx = \mu \quad \int (x - \mu)^2 p(x)dx = \sigma^2$$

- Constrained maximization is performed using Lagrangian multipliers. Maximize following functional wrt  $p(x)$ :  
$$-\int p(x) \ln p(x) dx + \lambda_1 (\int p(x) dx - 1) + \lambda_2 (\int xp(x) dx - \mu) + \lambda_3 (\int (x - \mu)^2 p(x) dx - \sigma^2)$$



# Maximising

- Using the calculus of variations derivative of functional is set to zero:

$$p(x) = \exp\{-1 + \lambda_1 + \lambda_2 x + \lambda_3 (x - \mu)^2\}$$

- Backsubstituting into three constraint equations leads to the result that distribution that maximizes differential is Gaussian

# Differential Entropy of Gaussian

- Distribution that maximizes Differential Entropy is Gaussian

$$p(x) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left\{\frac{-(x-\mu)^2}{\sigma^2}\right\}$$

- Value of maximum entropy is

$$H(x) = \frac{1}{2} \{1 + \ln(2\pi\sigma^2)\}$$

- Entropy increases as variance increases
- Differential entropy, unlike discrete entropy, can be negative for  $\sigma^2 < 1/(2\pi e)$

# Conditional Entropy

- If we have joint distribution  $p(x,y)$ 
  - We draw pairs of values of  $x$  and  $y$
  - If value of  $x$  is already known, additional information to specify corresponding value of  $y$  is  $-\ln p(y|x)$
- Average additional information needed to specify  $y$  is the conditional entropy

$$H[y | x] = -\iint p(y | x) \ln p(y | x) dy dx$$

# Conditional Entropy

- By product rule  $H[x,y] = H[y|x] + H[x]$ 
  - where  $H[x,y]$  is differential entropy of  $p(x,y)$
  - $H[x]$  is differential entropy of  $p(x)$
  - Information needed to describe  $x$  and  $y$  is given by information needed to describe  $x$  plus additional information needed to specify  $y$  given  $x$

# Relative Entropy

If we have modeled unknown distribution  $p(x)$  by approximating distribution  $q(x)$

- i.e.,  $q(x)$  is used to construct a coding scheme of transmitting values of  $x$  to a receiver
- Average additional amount of information required to specify value of  $x$  as a result of using  $q(x)$  instead of true distribution  $p(x)$  is given by relative entropy or K-L divergence

Important concept in Bayesian analysis

- Entropy comes from Information Theory
- *K-L Divergence*, or *relative entropy*, comes from Pattern Recognition, since it is a distance (dissimilarity) measure

# Relative Entropy or K-L Divergence

- Additional information required as a result of using  $q(x)$  in place of  $p(x)$

$$\begin{aligned} KL(p \parallel q) &= - \int p(x) \ln q(x) dx - \left( \int p(x) \ln p(x) dx \right) \\ &= - \int p(x) \ln \left\{ \frac{p(x)}{q(x)} \right\} dx \end{aligned}$$

- Not a symmetrical quantity:  $KL(p \parallel q) \neq KL(q \parallel p)$
- K-L divergence satisfies  $KL(p \parallel q) \geq 0$  with equality iff  $p(x) = q(x)$ 
  - Proof involves convex functions

# Convex Function

- A function  $f(x)$  is convex if every chord lies on or above function

- Any value of  $x$  in interval from  $x=a$  to  $x=b$  can be written as  $\lambda a + (1-\lambda)b$  where  $0 < \lambda < 1$

- Corresponding point on chord is

$$\lambda f(a) + (1-\lambda)f(b)$$

- Convexity implies

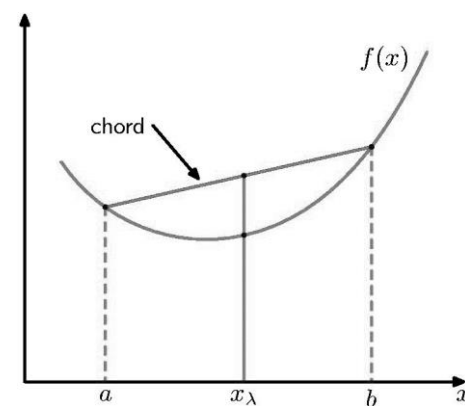
$$f(\lambda a + (1-\lambda)b) \leq \lambda f(a) + (1-\lambda)f(b)$$

Point on curve  $\leq$  Point on chord

- By induction, we get Jensen's inequality

$$f\left(\sum_{i=1}^M \lambda_i x_i\right) \leq \sum_{i=1}^M \lambda_i f(x_i)$$

where  $\lambda_i \geq 0$  and  $\sum_i \lambda_i = 1$



# Proof of positivity of K-L Divergence

- If we interpret  $\lambda_i$  as the probability distribution over a discrete variable  $x$  taking the values  $\{x_i\}$ :

$$f(E(x)) \leq E(f(x))$$

- For continuous variables:

$$f\left(\int xp(x)dx\right) \leq \int f(x)p(x)dx$$

$$KL(p||q) = -\int p(x) \ln \frac{p(x)}{q(x)} dx \geq -\ln \int q(x)dx = 0$$

$-\ln(x)$ :convex function

$$\int q(x)dx = 1$$

$$q(x) = p(x)$$

K-L divergence is a measure of the dissimilarity of two distributions



## Mutual Information

- Given joint distribution of two sets of variables  $p(x,y)$ 
  - If independent, will factorize as  $p(x,y)=p(x)p(y)$
  - If not independent, whether close to independent is given by
    - KL divergence between joint and product of marginals

$$\begin{aligned} I[x, y] &= KL(p(x, y) \parallel p(x)p(y)) \\ &= \iint p(x, y) \ln \left( \frac{p(x)p(y)}{p(x, y)} \right) dx dy \end{aligned}$$

- Called Mutual Information between variables  $x$  and  $y$

# Mutual Information

- From the properties of K-L divergence:

$$\begin{aligned} I[x, y] &= KL(p(x, y) \parallel p(x)p(y)) \\ &= \iint p(x, y) \ln \left( \frac{p(x)p(y)}{p(x, y)} \right) dx dy \geq 0 \end{aligned}$$

If and only if  $x$  and  $y$  are independent.

# Mutual Information

- Using Sum and Product Rules
  - $I[x,y] = H[x] - H[x|y] = H[y] - H[y|x]$ 
    - Mutual Information is reduction in uncertainty about
    - x given value of y (or vice versa)
- Bayesian perspective:
  - if  $p(x)$  is prior and  $p(x|y)$  is posterior, mutual information is reduction in uncertainty after y is observed